



# **A Low-Cost High-Speed Inspection System for Pharmaceutical Capsules**

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# Introduction

- Project in collaboration with Pharmaphil Inc. and the Ontario Centre of Excellence
- Solution to fix poor quality control of manufacturing process
- Retrofitting of existing capsule inspection system, Optisorter



# Current Quality Control

- Manual inspection performed on random samples from each run.
- Pre-packing inspection performed manually at high speed.
- Defective product is being shipped



# State of the Art



- Few capsule inspection systems exist
  - Very Expensive
  - Most use existing vision systems such as Cognex

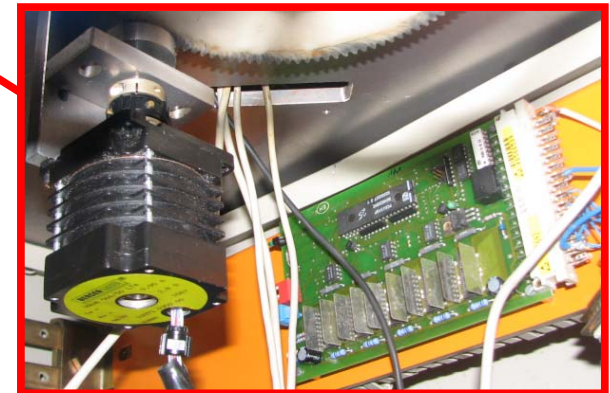
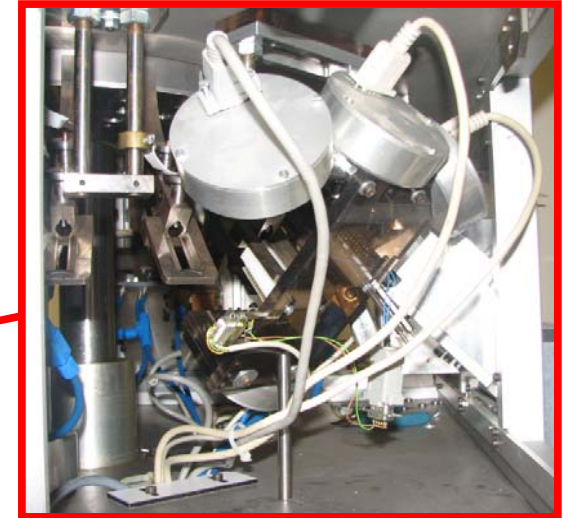
# Optisorter

- German designed system that inspects capsules
- Highly dated system but provides good mechanical base
- Electronics must be replaced
  - Analog PAL cameras
  - Equivalent 80286 CPUs
- Many controls and instrumentation can be reused
  - Electronic pneumatic valves
  - Stepper Motor / Controller
  - Power Supplies
  - Switches / Lamps





# Optisorter



# Optisorter

## System Summary

- Four quadrants work in parallel to inspect 1000 caps/min.
- Each quadrant has 3 cameras to capture a 360° view of the circumference of the capsule (120° separation).

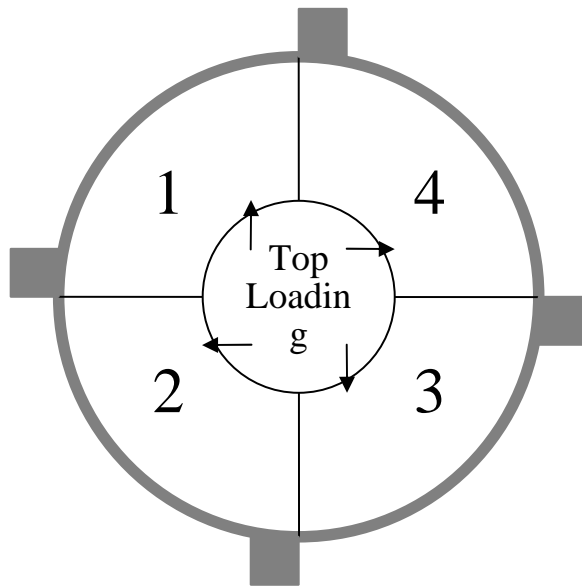


Fig 2. Optisorter Top View

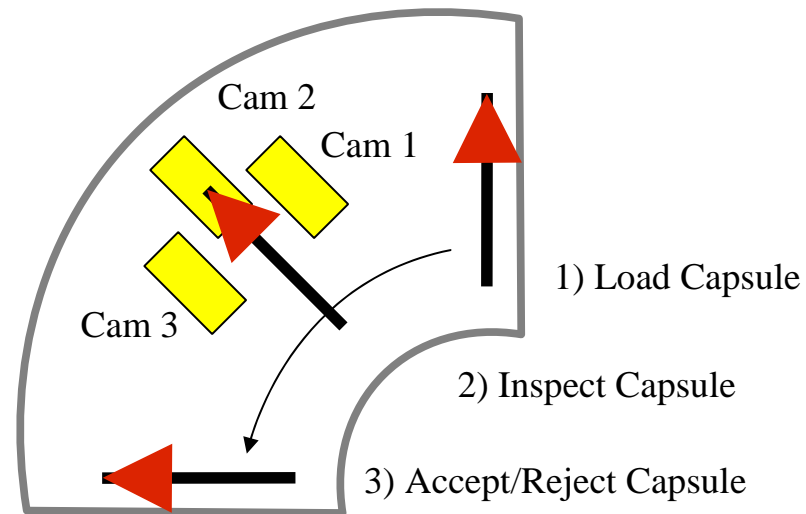
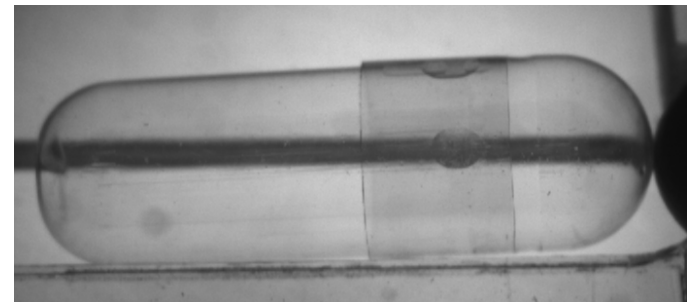


Fig 3. Quadrant 1 detail: Operational Flow

# Proposed System – Requirements

- Target Inspection rate of 1000 capsules per minute
- **Detect flaws including**
  - Incorrect Size / Colour
  - Dents
  - Cracks / Surface flaws
  - Holes
  - Missing Cap
  - Closed Capsule





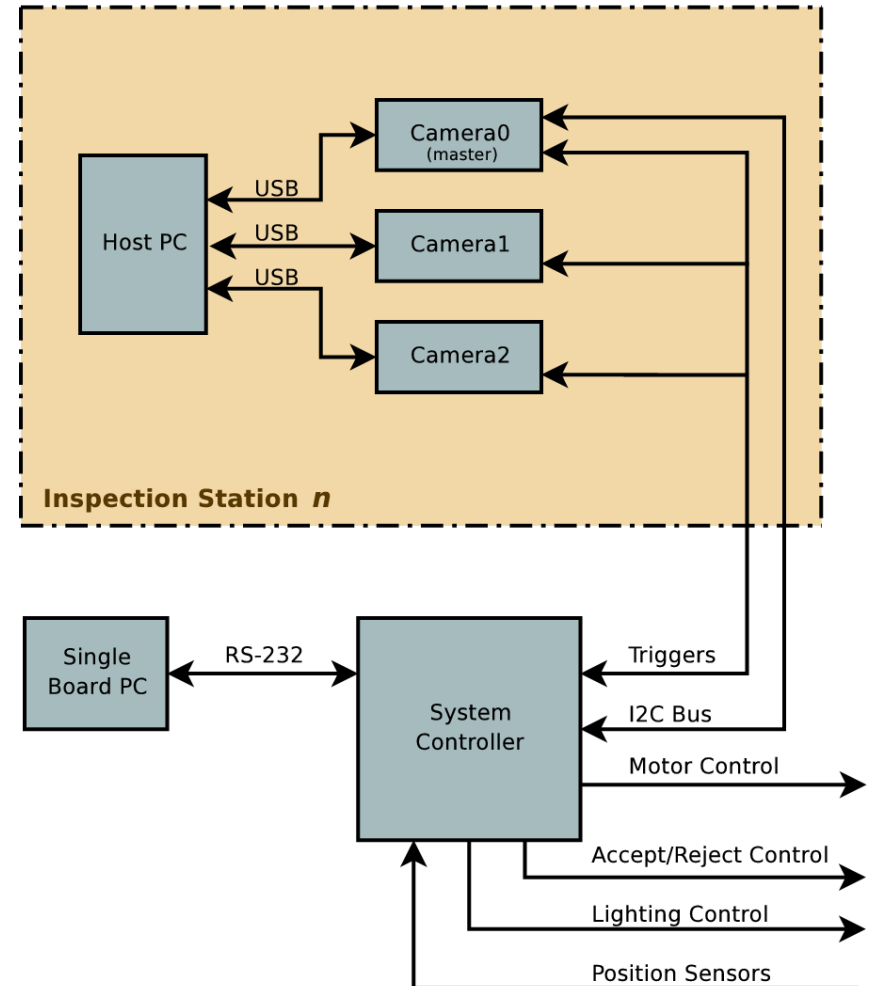


# Proposed System – Solution

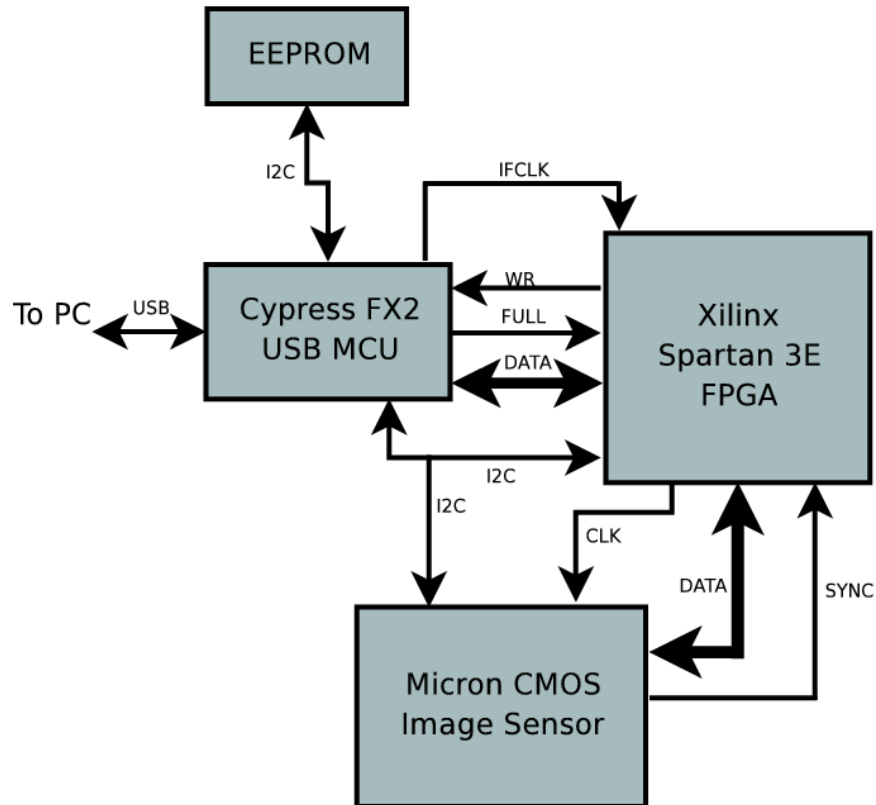
- Full Custom solution
- Development of custom hardware
  - Cameras
  - System controller
- Development of custom firmware and software
- Use of PCs to acquire image data and perform inspection

# Proposed System – Overview

- Four stations each with one host PC and 3 cameras.
- Stations communicate to System controller for triggers and accept and reject conditions
- System controller interfaces with Optisorter to control motor, actuators and switches.
- System controller also interfaces with Single board PC for external communication ie. Ethernet.



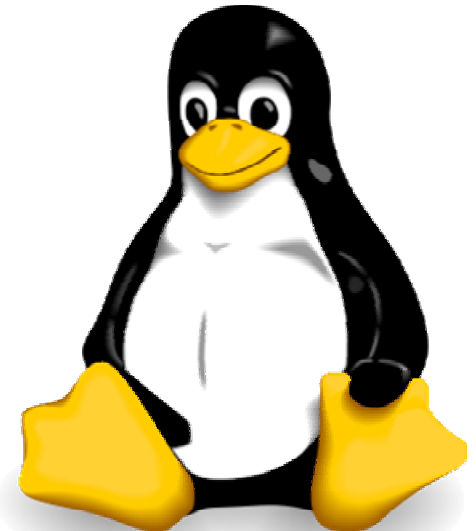
# Proposed System – USB2.0 Camera



- Custom design phases
  - Hardware design
  - PCB layout
  - PCB fabrication and population
  - Testing and verification
- USB 2.0 Interface for image transfer
  - Reliable and Fast (480Mbps)
  - Abundant

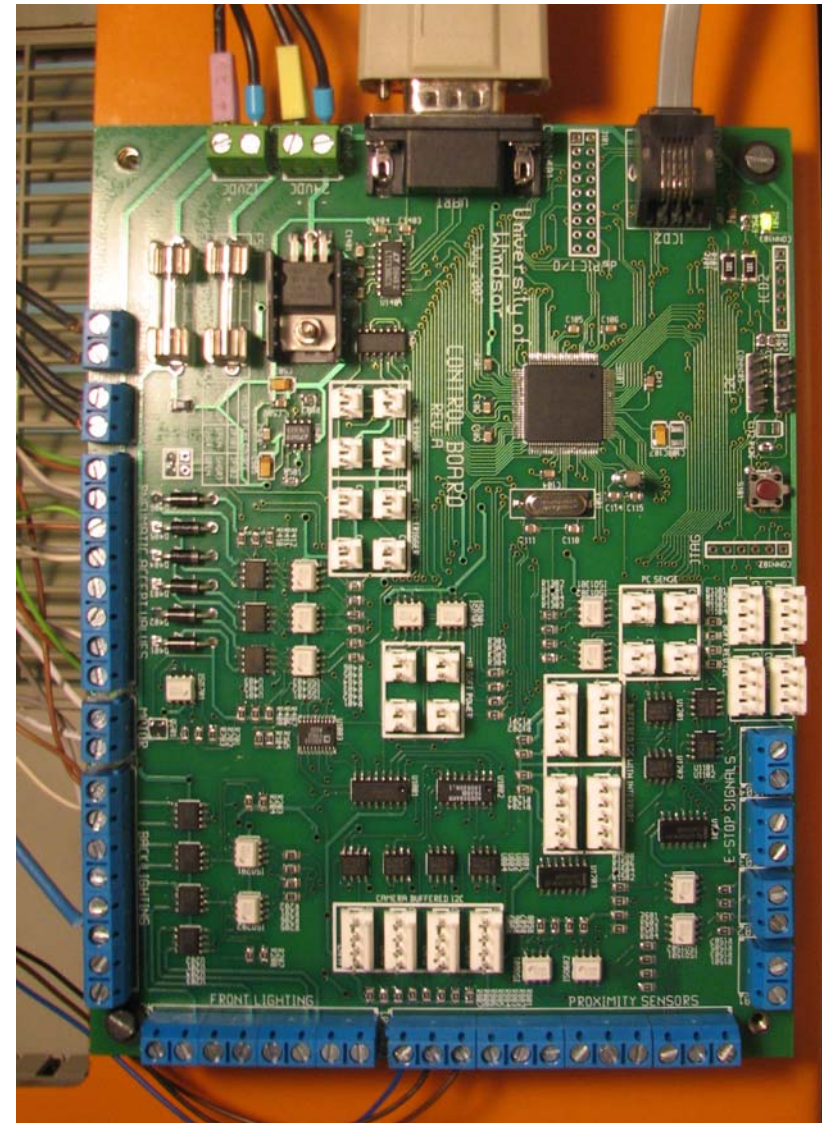
# Proposed System – Host PC

- Runs Linux distribution with 2.6 kernel
- Dedicated software running
  - Retrieves image data from USB cameras (using POSIX threads)
  - Performs inspection on all images acquired
  - Responds to the system with a pass / fail inspection result
- On system startup
  - Load firmware to all cameras



# Proposed System – System Controller

- Operates system controls
  - Motor Control
  - Capsule Accept / Reject Controls
  - Illumination / Camera Triggering
  - Emergency Stop Control
  - Communication interface to cameras
  - Provides a user interface
  - UART module to communicate with PC
  - Provides expansion module



# Proposed System – Camera

## Custom USB Camera

- Fully customized hardware
- Fully customized operation



## PROS

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- Flexible
- Application optimized
- Low Cost

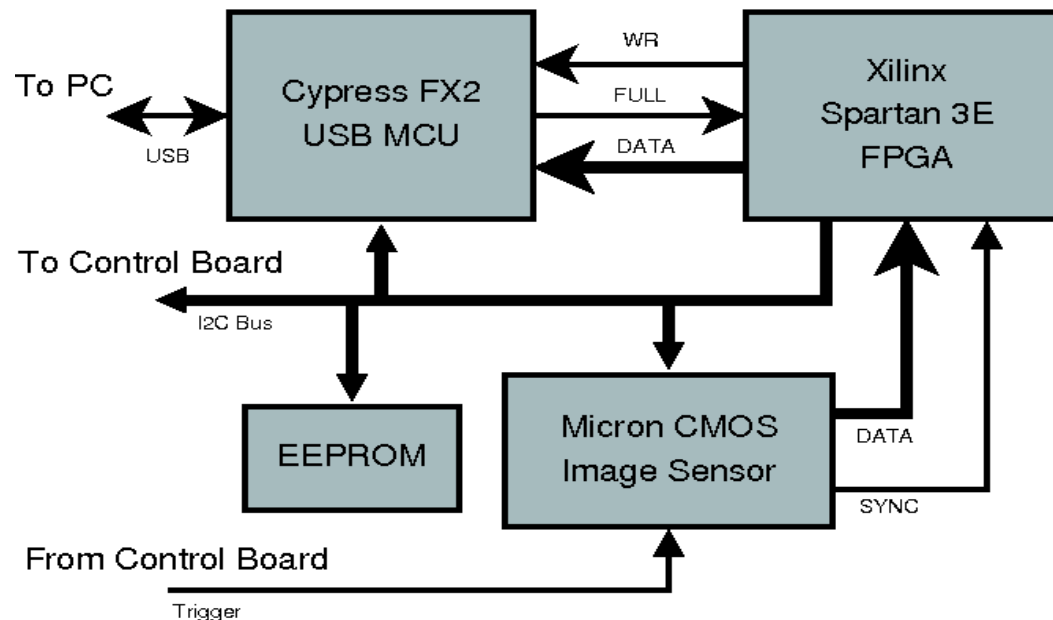
## CONS

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- Long development time

# Proposed System – Camera

- FX2 to handle data transfer to PC
- Micron CMOS captures image data
- Xilinx FPGA for image processing and construction
- EEPROM for ID information



# Proposed System – Camera

## Custom USB Camera – FPGA Functions

- Image synchronization
- Image interpolation (demosaicing )
- Color conversion and image enhancement
- FIFO to buffer data to FX2

